

# On a Monadic Encoding of Continuous Behaviour

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INESC TEC (HASLab) & Universidade do Minho

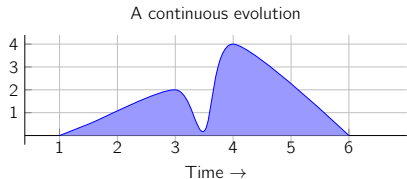
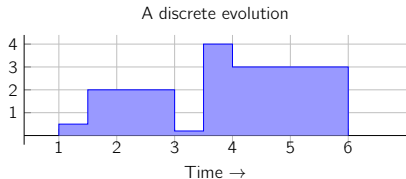
October 1, 2015

## The main goal

A coalgebraic calculus of hybrid components.

# Motivation & Context

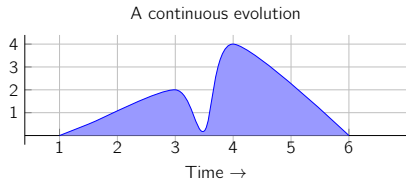
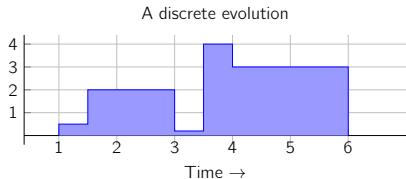
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- They are often complex
- but can be seen as the composition of (simpler) components.

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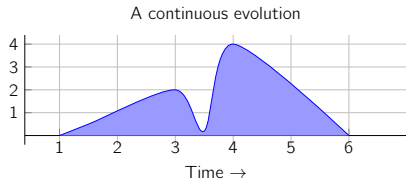
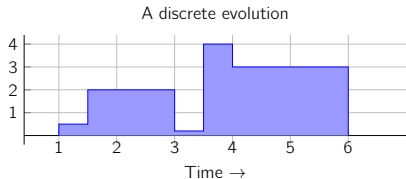
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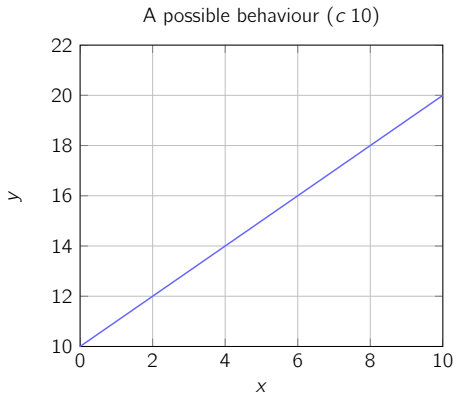
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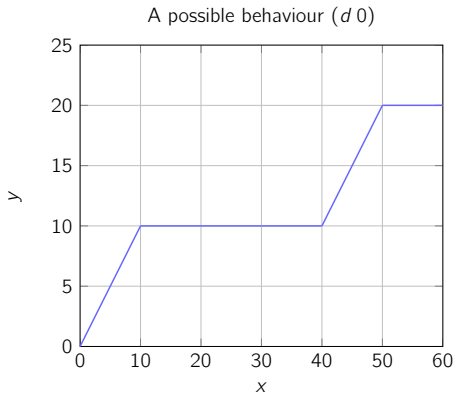


- They are often complex
- but can be seen as the composition of (simpler) components.

# Thermostat



# Water level regulator



## Hybrid components (coalgebraically)

Arrows of type  $S \times I \rightarrow S \times \mathcal{HO}$  where

- $S \times I \rightarrow S$  defines the **internal** (discrete) transitions
- and  $S \times I \rightarrow \mathcal{HO}$  the **observable** (continuous) behaviour.

This favours a coalgebraic perspective !



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## Coalgebras & Hybrid systems (related work)

- Object-oriented hybrid systems of coalgebras plus monoid actions [Jacobs, 2000]. A **coalgebra** for the (**discrete**) assignments, a **monoid** for the (**continuous**) evolutions.
- Notions of **bisimulation** for hybrid systems (resort to **open maps**) [Haghverdi et al., 2005].

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# Components as coalgebras

We view a component as

$$\langle s \in S, c : S \times I \rightarrow \mathcal{B}(S \times O) \rangle$$

where  $\mathcal{B}$  is a (strong) **monad** that captures a specific type of behaviour [Barbosa, 2001].

[Barbosa, 2001] shows how to generate a rich component algebra from a strong monad.

# Motivation & Context

Different monads capture different types of behaviour ...

...and thus different kinds of component

- Maybe monad ( $\mathcal{M}$ )  $\rightsquigarrow$  faulty components
- Powerset monad ( $\mathcal{P}$ )  $\rightsquigarrow$  non-deterministic components
- Distribution monad ( $\mathcal{D}$ )  $\rightsquigarrow$  probabilistic components
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## Monad $\mathcal{H}$

It is defined in such a way that

$$\frac{c : S \times I \rightarrow S \times \mathcal{H}O}{c : S \times I \rightarrow S \times (O^T \times D)} \text{ unfold } \mathcal{H}$$

where  $T = \mathbb{R}_{\geq 0}$  and  $D = [0, \infty]$ .

Kleisli composition allows the **transfer** of **evolution control** between components.

Technically, this amounts to **concatenation** of evolutions.

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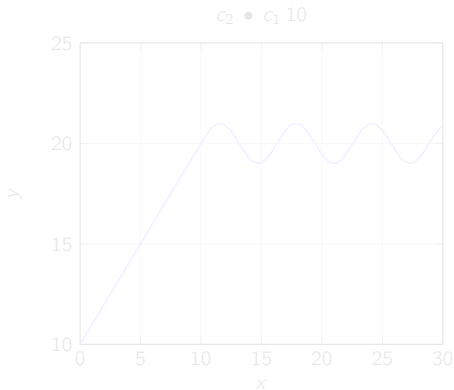
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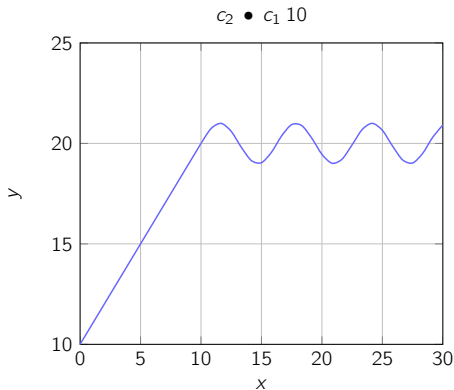
## Kleisli composition (thermostat revisited)

$$c_1 i = (\lambda t.(i + t), 10), \quad c_2 i = (\lambda t.(i + \sin t), \infty)$$



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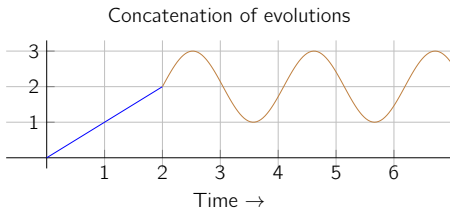
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# Monad $\mathcal{H}$ and Höfner's Algebra

Kleisli composition of Monad  $\mathcal{H}$  corresponds to concatenation of evolutions in

An algebra of hybrid systems [Höfner, 2009]



## Assembly of monad $\mathcal{H}$ (underlying functor)

Based upon the category of **topological** spaces **Top**.

### Definition

Given a space  $X \in |\mathbf{Top}|$ ,

$$\mathcal{H}X \cong \{ (f, d) \in X^T \times D \mid f \cdot \lambda_d = f \}$$

where  $\lambda_d = id \triangleleft \leq_d \triangleright \underline{d}$ .

### Definition

Given a continuous function  $g : X \rightarrow Y$ ,

$$\mathcal{H}g : \mathcal{H}X \rightarrow \mathcal{H}Y, \quad \mathcal{H}g \cong g^T \times id$$

Intuitively,  $\mathcal{H}g$  alters evolutions pointwise (but keeps durations).

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# Assembly of monad $\mathcal{H}$ (underlying functor)

An interesting algebra

$$\begin{array}{c} \mathcal{H}X \\ \downarrow \theta \\ X \end{array}$$

$$\theta(f, d) \cong f \circ 0$$

## Assembly of Monad $\mathcal{H}$ (monad operations)

$$\begin{array}{ccc} Id & & \mathcal{H}\mathcal{H} \\ & \searrow \eta & \swarrow \mu \\ & \mathcal{H} & \end{array}$$

### Definition

Given a space  $X \in |\mathbf{Top}|$ ,

$$\eta_X x \hat{=} (\underline{x}, 0)$$

Defines the **simplest** continuous system of type  $X \rightarrow \mathcal{H}X$ .

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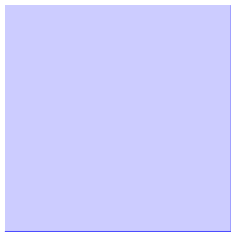
$$\mu_X (f, d) \hat{=} (\theta \cdot f, d) \# (f d)$$

...

# Assembly of Monad $\mathcal{H}$ (monad operations)

Let us reason

$$\begin{aligned} \mathcal{H}\mathcal{H}X &\subseteq \\ (\mathcal{H}X)^T \times D &\rightarrow \\ (\mathcal{H}X)^T &\subseteq \\ (X^T \times D)^T &\cong \\ (X^T)^T \times D^T &\rightarrow \\ (X^T)^T &\cong \\ X^{T \times T} & \end{aligned}$$



## Kleisli category $\mathbf{Top}_{\mathcal{H}}$

(An environment to study the effects of continuity over composition)

- $|\mathbf{Top}_{\mathcal{H}}| = |\mathbf{Top}|$ ,
- for any objects  $I, O \in |\mathbf{Top}_{\mathcal{H}}|$ ,

$$\mathbf{Top}_{\mathcal{H}}(I, O) = \mathbf{Top}(I, \mathcal{H}O)$$

- the identity of  $I$  is  $\eta_I$ , and given two arrows  $c_1 : I \rightarrow \mathcal{H}K$ ,  $c_2 : K \rightarrow \mathcal{H}O$  their (sequential) composition,

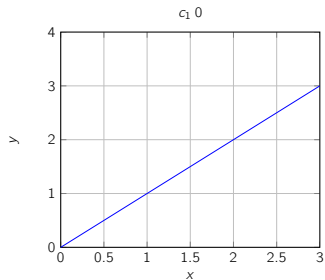
$$c_2 \bullet c_1 : I \rightarrow \mathcal{H}O$$

is equal to

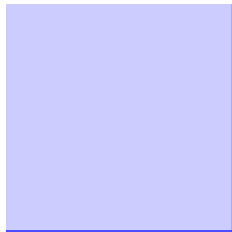
$$\mu \cdot \mathcal{H}c_2 \cdot c_1$$

# Kleisli composition (of $\mathbf{Top}_{\mathcal{H}}$ )

$$I \xrightarrow{c_1} \mathcal{H}K \xrightarrow{\mathcal{H}c_2} \mathcal{H}\mathcal{H}O \xrightarrow{\mu} \mathcal{H}O$$



$\mathcal{H}c_2$   
 $\mapsto$



## Other forms of composition (in $\mathbf{Top}_{\mathcal{H}}$ )

Choice (coproduct)

$$\frac{c_1 : I_1 \rightarrow \mathcal{H}O, c_2 : I_2 \rightarrow \mathcal{H}O}{[c_1, c_2] : I_1 + I_2 \rightarrow \mathcal{H}O} (+)$$

Parallelism (pullback)

$$\frac{c_1 : I \rightarrow \mathcal{H}O_1, c_2 : I \rightarrow \mathcal{H}O_2}{\langle\langle c_1, c_2 \rangle\rangle : I \rightarrow \mathcal{H}(O_1 \times O_2)} (\times)$$

These operators are (co)limits, hence a number of useful laws come for free !



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Synchronised parallelism

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Feedback

$$\frac{c : I \rightarrow \mathcal{H}I}{\nu c : I \rightarrow \mathcal{H}I} \quad (\nu)$$

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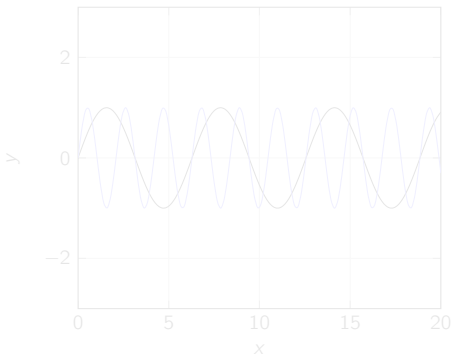
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## Top<sub>ℋ</sub> (Parallelism)

$$c_1 x = (\lambda t. x + (\sin t), 20)$$

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$\langle\langle c_1, c_2 \rangle\rangle 0$

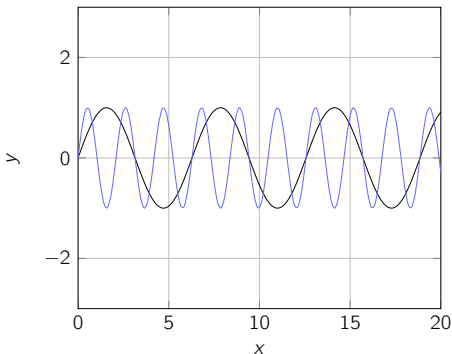


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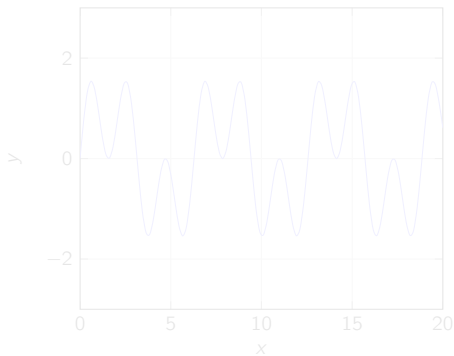
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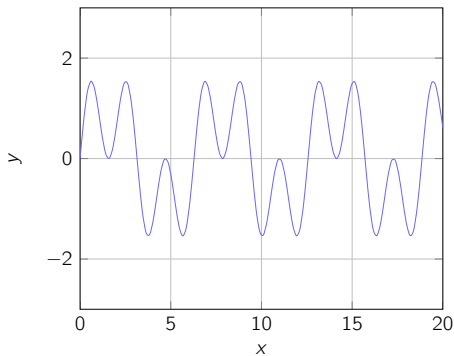
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# Conclusions

- Our goal is a **coalgebraic** calculus of **hybrid components**
- and monad  $\mathcal{H}$  seems to be a promising approach for this.

## But mind

- **Simulink**, widely used in industry, and
- **Hybrid automata**, the standard **formalism** for the specification of hybrid systems.
  
- The former is highly expressive, but lacks a clear semantics.
- The latter is very intuitive, but does not have composition mechanisms as rich as Simulink.

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# References I

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